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THE MATHEMATICAL MODELLING OF THE NONLINEAR HEAT TRANSPORT IN THIN PLATE

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ABSTRACT

The approximations of the nonlinear heat transport problem are based on the finite volume **(FM)** and averaging **(AM)** methods [1,2]. This procedures allows reduce the nonlinear 2-D problem for partial differential equation (PDE) to a initial-value problem for a system of 2 nonlinear ordinary differential equations(ODE) of first order in the time t or to a initial-value problem for one nonlinear ODE of first order with two nonlinear algebraic equations.

1. MATHEMATICAL MODEL

We shall consider the nonlinear initial-boundary value problem in the following form:

$$\partial u/\partial t + v_0 \partial u/\partial x = \partial (\lambda \partial u/\partial x)/\partial x + F(x, t, u),$$

$$x \in (0, l), \ t > 0, \tag{1.1}$$

$$\lambda \partial u(0,t) / \partial x = f_1(t, u(0,t)), \quad t \ge 0, \tag{1.2}$$

$$\lambda \partial u(l,t) / \partial x = f_2(t, u(l,t)), \quad t \ge 0, \tag{1.3}$$

$$u(x,t) = u^{0}(x), \quad x \in [0,l],$$
(1.4)

where u(x,t), $u^0(x)$ are the temperature, v_0 is the transfer velocity ($v_0 = const$), l is the thin of the plate ($l \ll 1$), λ is the conductivity ($\lambda = const$). The function F is the nonlinear heating source arising in chemical reactions, for example in the form

$$F = AHc(u)exp(-E/(Ru)),$$

where c, E, H are the concentration, activation energy of the burning substance and heat of combustion reaction, R is the universal gas constant 8.31441J/(K, mol), respectively. A is the "pre-exponential" Arhennius factor. The nonlinear functions f_1, f_2 in boundary conditions (1.2), (1.3) describe the radiation from the heaters and the convection, for example

$$f_1 = \alpha_0 (u - T_0) + \epsilon_0 \sigma (u^4 - \theta_0^4),$$

$$f_2 = -\alpha_1 (u - T_1) - \epsilon_1 \sigma (u^4 - \theta_1^4),$$

where α_0, α_1 are the convective heat transfer coefficients, T_0, T_1 are the temperature of the environment, θ_0, θ_1 denote the temperature of the heaters, ϵ_0, ϵ_1 are the coefficients of emissivity, σ is the Stefan-Boltzmann constant $5.670310^{-8}W/(m^2.K^4)$.

In order to derive the approximate equations we write the PDE (1.1) in the following self-adjoint form

$$\partial W^*(x,t)/\partial x = G^*(x,t,u), \tag{1.5}$$

where $W^* = \lambda e(x) \partial u / \partial x$ is the general flux-function,

$$\begin{split} G^* &= e(x)G(x,t,u), \quad e(x) = exp(-v_0(x-b)/\lambda), \quad b = const, \\ G &= \partial u/\partial t - F(x,t,u). \end{split}$$

2. THE FM METHOD

To derive finite-difference equations associated with the grid points x = 0, and x = l we integrate the differential equation (1.5) from x = 0 to x = l/2 (b = 0) and from x = l/2 to x = l (b = l). Therefore we have the integral forms of the conservation law to the intervals (0, l/2) and (l/2, l).

The nonlinear 2-point difference equations are in the following form:

$$\lambda l^{-1} g(\beta)(u_1(t) - u_0(t)) - f_1(t, u_0(t)) = R_0, \qquad (2.1)$$

$$f_2(t, u_1(t)) - \lambda l^{-1} g(-\beta)(u_1(t) - u_0(t)) = R_1, \qquad (2.2)$$

where

$$u_0(t) = u(0, t), \quad u_1(t) = u(l, t), \quad \beta = v_0 l/\lambda,$$

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$$\begin{split} g(\beta) &= \beta/(\exp(\beta) - 1) = 1 - \beta/2 + \beta^2/12 - \beta^4/720 + O(\beta^6), \\ R_j &= \int_0^l K_j(x) G(x, t, u(x, t)) dx, \quad j = 0, 1, \\ K_0(x) &= \exp(\beta(1 - x/l)) - 1)/(\exp(\beta) - 1) \in [0, 1], \\ K_1(x) &= (1 - \exp(-\beta x/l))/(1 - \exp(-\beta)) \in [0, 1]. \end{split}$$

For the given function G the equations (2.1), (2.2) are the exact approximations for unknown functions $u_0(t), u_1(t)$. For the approximation of the right side integrals R_0, R_1 we consider the following quadrature formulas:

$$R_0 = l(A_0G_0 + A_1G_1) + r_0(\eta), \qquad (2.3)$$

$$R_1 = l(A_0^*G_0 + A_1^*G_1) + r_1(\eta), \qquad (2.4)$$

where the error terms are given by

$$\begin{split} r_{0}(\eta) &= 0.5\partial^{2}G/\partial x^{2}|_{x=\eta}l^{3}E_{0}, \\ r_{1}(\eta) &= 0.5\partial^{2}G/\partial x^{2}|_{x=\eta}l^{3}E_{0}^{*}, \quad \eta \in (0,1), \\ G_{0} &= G(0,t,u_{0}(t)), G_{1} = G(l,t,u_{1}(t)), \eta \in (0,l), \\ A_{0} &= g_{3}(\beta), A_{1} = g_{2}(\beta), A_{0}^{*} = g_{2}(-\beta), A_{1}^{*} = g_{3}(-\beta), \\ E_{0} &= g_{4}(\beta), E_{0}^{*} = g_{4}(-\beta), \\ g_{2}(\beta) &= \beta^{-2}(1-(1+\beta/2)g(\beta)) \\ &= 1/6-\beta/24+\beta^{2}/720+\beta^{3}/1440+O(\beta^{4}), \\ g_{3}(\beta) &= \beta^{-1}-\beta^{-2}(1-(1-\beta/2)g(\beta)) \\ &= 1/3-\beta/24-\beta^{2}/720+\beta^{3}/1440+O(\beta^{4}), \\ g_{4}(\beta) &= \beta^{-3}(2-\beta-(2-\beta^{2}/6)g(\beta)) \\ &= -1/12+\beta/60-\beta^{3}/3360+O(\beta^{5}). \end{split}$$

In the limit case for $v_0 = 0$ we have $\beta = 0$. Therefore for the approximate solutions $y_0(t), y_1(t)$, deleting the error terms r we have from (2.3), (2.4) the following system of nonlinear first order ODE:

$$\dot{y}_0 = F(0, t, y_0) + (l\Delta)^{-1} [\lambda l^{-1} (y_1 - y_0) g_1(\beta) -g_3(-\beta) f_1(t, y_0) - g_2(\beta) f_2(t, y_1)],$$
(2.5)

$$\dot{y}_1 = F(l, t, y_1) - (l\Delta)^{-1} [\lambda l^{-1} (y_1 - y_0) g_1(-\beta) - g_3(\beta) f_2(t, y_1) - g_2(-\beta) f_1(t, y_0)],$$
(2.6)

where

$$g_{1}(\beta) = g_{3}(\beta)g(\beta) + g_{2}(\beta)g(-\beta) = \beta^{-1}(1 - g(\beta)) = 1/2 - \beta/12 + \beta^{3}/720 + O(\beta^{5}), \Delta = g_{3}(\beta)g_{3}(-\beta) - g_{2}(\beta)g_{2}(-\beta) = \beta^{-1}(0.5 - g_{1}(\beta)) = 1/12 - \beta^{2}/720 + \beta^{4}/30240 + O(\beta^{6}).$$

The functions g, g_1, g_2, g_3 are positive monotone decreasing and they have the following properties:

$$\begin{split} g(-\infty) &= +\infty, \quad g_1(-\infty) = 1, \quad g_2(-\infty) = g_3(-\infty) = 0.5, \\ g_j(\infty) &= 0, \quad j = 0, 1, 2, 3, \quad g_0 = g. \end{split}$$

The function g_4 is negative monotone increasing and it satisfies the conditions

$$g_4(-\infty) = -1/6, \quad g_4(\infty) = 0,$$

and the error terms can be estimated as

$$|r_j(\eta)| \le M_2 l^3 / 12, \quad j = 1, 2,$$

where $|\partial^2 G/\partial x^2| \leq M_2 = const.$ The system (2.5), (2.6) must be solved with the initial conditions

$$y_0(0) = u^0(0), \quad y_1(0) = u^0(l).$$

3. THE AM METHOD

Using the parabolic distribution for the approximation of the function y in the x direction

$$y(x,t) = \bar{y}(t) + \delta(t)(xl^{-1} - 1/2) + \gamma(t)(x^2l^{-2} - 1/3)$$
(3.1)

we integrate equation (1.5) from x = 0 to x = l, (b = l/2) and divide this expression by l:

$$l^{-1}[exp(-\beta/2)f_2(t,u(l,t)) - exp(\beta/2)f_1(t,u(0,t))] = R_3, \qquad (3.2)$$

where

$$\bar{y}(t) = l^{-1} \int_0^l y(x,t) dx$$

is the average value,

$$R_3 = l^{-1} \int_0^l exp(-\beta(x-l/2)/l)G(x,t,u(x,t))dx.$$

At every time moment t the unknown functions $\delta(t)$, $\gamma(t)$ can be obtained from boundary conditions (1.2), (1.3) and from expression (3.1) in the form of two nonlinear algebraic equations:

$$\lambda l^{-1} \delta(t) = f_1(t, y_0(t)), \tag{3.3}$$

$$\lambda l^{-1}(\delta(t) + 2\gamma(t)) = f_2(t, y_1(t)), \qquad (3.4)$$

where

$$y_0(t) = \bar{y}(t) - \delta(t)/2 - \gamma(t)/3, \quad y_1(t) = \bar{y}(t) + \delta(t)/2 + 2\gamma(t)/3,$$

or

$$\gamma = 3(y_0 + y_1 - 2\bar{y}), \qquad \delta = 6\bar{y} - 4y_0 - 2y_1,$$

We can represent integral R_3 in the form

$$R_3 = A_0 l^{-1} \int_0^l G dx + l B_0 \partial G / \partial x |_{x=\eta}, \quad \eta \in (0, l),$$

where

$$A_0 = 2\beta^{-1}sh(\beta/2), \quad B_0 = A_0/\beta - \beta^{-1}ch(\beta/2).$$

Therefore we have the initial-value problem for nonlinear first order ODE :

$$\dot{\bar{y}}(t) = F(t, \bar{y}(t)) + l^{-1}(g(\beta)f_2(t, y_1(t)) - g(-\beta)f_1(t, y_0(t)),
\bar{y}(0) = l^{-1} \int_0^l u^0(x)dx.$$
(3.5)

This problem must be solved together with algebraic equations (3.3). The simplest form of the AM-method yields nonlinear ODE (3.4) with $y_1 = y_0 = \bar{y}$ ($\delta = \gamma = 0$).

4. NUMERICAL RESULTS

We consider the process of glass fabric manufacturing (with thickness l = 0.1mm) at the glass fiber plant in the Valmiera city (Latvia). An oil must be removed by heating and burning process[1,3]. The initial-boundary value problem for nondimensional system of PDE ($x = \tilde{x}l, c = \tilde{c}c_0, u = \tilde{u}\theta_0, v_0 = 0, T_0 = T_1, \alpha_0 = \alpha_1, \epsilon_0 = \epsilon_1$, the "wave" symbol is deleted) is in the following form:

$$\begin{aligned} \partial u/\partial t &= a_1 \partial^2 u/\partial x^2 + a_7 c \ ex(u), \\ \partial c/\partial t &= -a_8 c \ ex(u), \\ f_1(t, u(0, t)) &= a_2(u^4(0, t) - 1) + 0.5 a_3(u(0, t) - a_4), \\ f_2(t, u(1, t)) &= a_2(a_5 - u^4(1, t)) + 0.5 a_3(a_4 - u(1, t)), \\ u(x, 0) &= a_6, \qquad c(x, 0) = 1, \end{aligned}$$

$$(4.1)$$

where

$$ex(u) = exp(a_9(1 - u^{-1})), \ a_1 = \lambda l^{-2} = 160.415, \ a_2 = \sigma \epsilon_0 \theta_0^3 / l = 1.72, a_3 = 2\alpha_0 / l = 0.06, \ a_4 = T_0 / \theta_0 = 0.8842, \ a_5 = (\theta_1 / \theta_0)^4 = 0.5635, a_6 = u^0 / \theta_0 = 0.2698, \ a_7 = c_0 HAexp(-E/(R\theta_0)) / \theta_0 = 51.26, a_8 = Aexp(-E/(R\theta_0)) = 128.68, \ a_9 = E/(R\theta_0) = 17.14,$$

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 c_0 is the initial concentration of oil. The ODE for the concentration of oil has the form

$$\dot{c}(t) = -a_8 \ c(t) \ ex(u), \tag{4.2}$$

where $c = c(0, t) = c_0(t)$ and $c = c(1, t) = c_1(t)$ for the FM method, $c = \bar{c}(t)$ for the AM method.

The numerical solutions of the stiff problems of ODE (2.5), (2.6), (3.4), (4.2) are obtained with the routines "gear", "mgear", "lsode" of "MAPLE". Figure 1 shows typical results of calculations: the fabric temperature rises to the maximum value and the oil concentration is falling to zero over a "burning zone" in the time interval [0.26, 0.31].

In the table 1 we can see the numerical values of temperature $y_0(t)$, $y_1(t)$ in this zone, obtained by the **FM** and **AM**.



Figure 1. The graphics of the temperature \bar{y} and the concentration *c*.

The values of the concentration c are the following

Table 1.The values of temperatures for the FM and AM.

t	$y_0(AM)$	$y_1(AM)$	$y_0(FM)$	$y_1(FM)$
0.26	0.8754	0.8731	0.8769	0.8745
0.27	0.9470	0.9448	0.9526	0.9501
0.28	1.1929	1.1907	1.1932	1.1910
0.29	1.1551	1.1530	1.1550	1.1527
0.30	1.1244	1.1221	1.1240	1.1218
0.31	1.0991	1.0970	1.0986	1.0963

- 1) $c_0(0.26) = 0.8457, c_1(0.26) = 0.8538, \bar{c}(0.26) = 0.8532,$
- 2) $c_0(0.27) = 0.6616, c_1(0.27) = 0.6761, \bar{c}(0.27) = 0.6824,$
- 3) $c \le 10^{-4}, t \ge 0.28.$

For testing the methods we consider only heating process $(A = a_8 = a_7 = 0)$. Then the temperature distribution u(x, t) can be obtained from (4.1) by using the Laplace transform for value t in the form of a sequence of functions $u_m(1, t), m = 1, 2, 3, \ldots$, which are the solutions to nonlinear the system of Volterra integral equations of the second kind.

The results of the comparison are given in the table 2 $(u_0, u_1 \text{ are the exact} values by <math>m = 6)$.

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NETIESINIO ŠILUMOS PERNEŠIMO PLONOSE PLOKŠTELĖSE MATEMATINIS MODELIAVIMAS

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Darbe sprendžiamas netiesinis šilumos pernešimo uždavinys. Uždavinio specifika yra ta, kad šilumos pernešimas vyksta labai plonose plokštelėse, todėl nagrinėjamas vienmatis apibendrintas modelis. Ši redukcija atliekama baigtinių tūrių ir vidurkinimo metodais. Gautoji dviejų netiesinių paprastųjų diferencialinių lygčių sistema yra sprendžiama skaitiškai. Išnagrinėtas ir alternatyvus varijantas, kai po redukcijos gaunama viena netiesinė paprastoji diferencialinė lygtis bei dvi papildomos algebrinės lygtys.

Table 2.Comparison of the numerical results.

t	$y_0(AM)$	$y_1(AM)$	$y_0(FM)$	$y_1(FM)$	u_0	u_1
0.1	.5330	.5299	.5318	.5295	.53262	.53044
0.2	.7412	.7388	.7408	.7385	.74106	.73889
0.3	.8621	.8603	.8622	.8599	.86202	.85987
0.4	.9139	.9123	.9139	.9116	.91365	.91150
0.5	.9321	.9309	.9322	.9299	.93208	.92993

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