EXPRESSIONS OF SOLUTIONS OF ORDINARY DIFFERENTIAL EQUATIONS BY STANDARD FUNCTIONS

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Abstract. It is well known that solutions of many ordinary differential equations allow presentation in the power series form. In the paper we introduce and analyze rigorous conditions under which the later series (solutions) can be reduced to a finite sum of standard functions. Some areas of practical applicability of the proposed algorithm are discussed.

Key words: differential equations, algebraic progression, Van-der-Mond determinant, standard functions

1. Introduction

Various dynamical systems are described by ordinary differential equations. The power series solutions of these equations can be easily obtained using the operator method [1]. These series must be changed to polynomials with optional order in the case of a computer realization. It is possible to approximate those polynomials by a finite sum of exponential functions, provided solutions themselves are periodic or aperiodic functions, [2].

In the paper, representation of solutions in the form of a finite sum of standard functions is discussed. A new computational algorithm for discarding of non-significant terms, depending on accuracy prescribed, is presented. The developed approach has been successfully applied to solve a system of ordinary differential equations, used to describe reduction of wind or wave power into electrical energy. In the paper, the model has links with self-vibrations that are transformed into rotational motion. To say more, implementation of trigonometric functions not only facilitates evaluation of dynamical characteristics but also makes determination of the existence domains for steady modes more precise.

2. The General Part

All the necessary notations, definitions and theorems associated with formulation of conditions, under which the power series solution of a differential equation can be reduced to a finite sum of standard functions, are presented below. In particular, the Newton's binomial coefficients and relevant expressions are to be used for $j, k \in \mathbb{Z}_0$:

2.1. The Van-der-Mond determinants

The Van-der-Mond determinant, as well as its generalized version, is introduced in this section. Let us note, that Van-der-Mond determinants are different from zero for all possible values of their elements.

DEFINITION 1. The set of numbers $\lambda_1, \lambda_2, \dots, \lambda_n \in C, n \in N$, is called *Vander-Mond set* (i.e. *V*-set), provided $\lambda_k \neq \lambda_r$ for $k \neq r$.

Whatever the V-set, non-zero Van-der-Mond determinant can be written as:

$$V_{n}(\lambda_{1}, \lambda_{2}, \dots, \lambda_{n}) := \begin{vmatrix} 1 & \lambda_{1} & \lambda_{1}^{2} & \dots & \lambda_{1}^{n-1} \\ 1 & \lambda_{2} & \lambda_{2}^{2} & \dots & \lambda_{2}^{n-1} \\ \dots & \dots & \dots & \dots \\ 1 & \lambda_{n} & \lambda_{n}^{2} & \dots & \lambda_{n}^{n-1} \end{vmatrix} = (\lambda_{2} - \lambda_{1})(\lambda_{3} - \lambda_{1})(\lambda_{3} - \lambda_{2}) \\ \times \dots (\lambda_{n} - \lambda_{1})(\lambda_{n} - \lambda_{2}) \dots (\lambda_{n} - \lambda_{n-1}) \neq 0. \quad (2.2)$$

Obviously, $V_1(\lambda_1) = 1$.

Let $\{\hat{\lambda}_1, \hat{\lambda}_2, \dots, \hat{\lambda}_m\}$ be a V-set. Consider the following expressions:

$$\Delta_k^{(0)}(j) := \hat{\lambda}_k^j, \quad \Delta_k^{(r+1)}(j) := \frac{\Delta_{k+1}^{(r)}(j) - \Delta_k^{(r)}(j)}{\hat{\lambda}_{k+r+1} - \hat{\lambda}_k},$$

$$r = 0, 1, \dots; \quad 1 \le k \le m - r - 1. \quad (2.3)$$

It can be easily seen that these expressions (thoroughly described in [3]) are symmetric polynomials with the same degree terms in $\hat{\lambda}_1, \hat{\lambda}_2, \dots, \hat{\lambda}_m$. For instance,

$$\Delta_k^{(1)}(0) := 0, \ \Delta_k^{(1)}(j) := \frac{\hat{\lambda}_{k+1}^j - \hat{\lambda}_k^j}{\hat{\lambda}_{k+1} - \hat{\lambda}_k} = \sum_{\substack{k, l \in Z_0, \\ k+l = j-1}}^{j-1} \hat{\lambda}_k^k \hat{\lambda}_{k+1}^l, \ j = 1, 2, 3, \dots,$$

$$\Delta_k^{(2)}(0) = \Delta_k^{(2)}(1) = 0,$$

$$\Delta_k^{(2)}(j) := \frac{\hat{\lambda}_{k+2}^j - \hat{\lambda}_{k+1}^j}{\hat{\lambda}_{k+2}^j - \hat{\lambda}_{k+1}^j} - \frac{\hat{\lambda}_{k+1}^j - \hat{\lambda}_{k}^j}{\hat{\lambda}_{k+1}^j - \hat{\lambda}_{k}^j}}{\hat{\lambda}_{k+2}^j - \hat{\lambda}_{k}} = \sum_{\substack{k, l, r \in Z_0 \\ k+l+r=j-2}}^{j-1} \hat{\lambda}_k^k \hat{\lambda}_{k+1}^l \hat{\lambda}_{k+2}^r, \quad j \ge 2.$$

On the basis of (2.1), (2.2) and (2.3), the following relationships are obtained:

$$\Delta_{k}^{(0)}(j) = \frac{1}{V_{1}(\hat{\lambda}_{k})\hat{\lambda}_{k}^{j}}, \quad \Delta_{k}^{(r+1)}(j) := \frac{1}{V_{r+2}(\hat{\lambda}_{k}, \hat{\lambda}_{k+1}, \dots, \hat{\lambda}_{k+r+1})} \Big(\gamma_{r+1r+1} \\ \times V_{r+1}(\hat{\lambda}_{k}, \hat{\lambda}_{k+1}, \dots, \hat{\lambda}_{k+r}) \hat{\lambda}_{k+r+1}^{j} + \gamma_{r+1r} V_{r+1}(\hat{\lambda}_{k}, \dots, \hat{\lambda}_{k+r-1}, \hat{\lambda}_{k+r+1}) \\ \times \hat{\lambda}_{k+r}^{j} + \dots + \gamma_{r+10} V_{r+1}(\hat{\lambda}_{k+1}, \hat{\lambda}_{k+2}, \dots, \hat{\lambda}_{k+r+1}) \hat{\lambda}_{k}^{j} \Big),$$
(2.4)

where $\gamma_{r+1l} = (-1)^{r+1+l}, \quad l = 0, 1, \dots, r+1.$

For the coefficients γ_{r+1l} , we have

$$\gamma_{r+1r+1}\gamma_{r+1r}\cdots\gamma_{r+10} = (-1)^{\binom{r+1}{2}}, \tag{2.5}$$

where the Van-der-Mond determinants satisfy the relationship

$$V_{r}(\hat{\lambda}_{k}, \hat{\lambda}_{k+1}, \dots, \hat{\lambda}_{k+r-1}) V_{r}(\hat{\lambda}_{k}, \dots, \hat{\lambda}_{k+r-2}, \hat{\lambda}_{k+r}) \cdots$$

$$\times V_{r}(\hat{\lambda}_{k+1}, \hat{\lambda}_{k+2}, \dots, \hat{\lambda}_{k+r}) = V_{r+1}^{r-1}(\hat{\lambda}_{k}, \hat{\lambda}_{k+1}, \dots, \hat{\lambda}_{k+r}), \quad r \ge 1.$$
(2.6)

For instance,

$$\Delta_{k}^{(1)}(j) = \frac{1}{V_{2}(\hat{\lambda}_{k}, \hat{\lambda}_{k+1})} \left(V_{1}(\hat{\lambda}_{k}) \hat{\lambda}_{k+1}^{j} - V_{1}(\hat{\lambda}_{k+1}) \hat{\lambda}_{k}^{j} \right),$$

$$\Delta_{k}^{(2)}(j) = \frac{1}{(\hat{\lambda}_{k+2} - \hat{\lambda}_{k})(\hat{\lambda}_{k+2} - \hat{\lambda}_{k+1})} \hat{\lambda}_{k+2}^{j} - \frac{1}{(\hat{\lambda}_{k+1} - \hat{\lambda}_{k})(\hat{\lambda}_{k+2} - \hat{\lambda}_{k+1})} \hat{\lambda}_{k+1}^{j}$$

$$\frac{1}{(\hat{\lambda}_{k+1} - \hat{\lambda}_{k})(\hat{\lambda}_{k+2} - \hat{\lambda}_{k})} \hat{\lambda}_{k}^{j} = \frac{1}{V_{3}(\hat{\lambda}_{1}, \hat{\lambda}_{2}, \hat{\lambda}_{3})} \left(V_{2}(\hat{\lambda}_{k}, \hat{\lambda}_{k+1}) \hat{\lambda}_{k+2}^{j} - V_{2}(\hat{\lambda}_{k}, \hat{\lambda}_{k+2}) \hat{\lambda}_{k+1}^{j} + V_{2}(\hat{\lambda}_{k+1}, \hat{\lambda}_{k+2}) \hat{\lambda}_{k}^{j} \right), \quad j = 0, 1, 2, \cdots.$$

Since $\Delta_j^{(r)}$ are polynomials in $\hat{\lambda}_1, \hat{\lambda}_2, \dots, \hat{\lambda}_m$, the following limit is valid

$$\lim_{\hat{\lambda}_k, \hat{\lambda}_{k+1}, \dots, \hat{\lambda}_{k+r} \to \lambda_k} \Delta_k^{(r)}(j) = {j \choose r} \lambda_k^{j-r}.$$
 (2.7)

Now, let $\{\hat{\lambda}_1, \hat{\lambda}_2, \dots, \hat{\lambda}_n\}$ and $\{\lambda_1, \lambda_2, \dots, \lambda_m\}$ be two V-sets and m_1, m_2, \dots, m_n be natural numbers, satisfying the condition

$$m_1 + m_2 + \ldots + m_n = m.$$

Then, by using $\hat{\lambda}_1, \hat{\lambda}_2, \dots, \hat{\lambda}_m$ and expressions $\Delta_k^{(r)}(j)$ we get the following form of the determinant

$$\Phi_{m_1,m_2,\ldots,m_n}(\hat{\lambda}_1,\hat{\lambda}_2,\ldots,\hat{\lambda}_m) := \begin{vmatrix} \Delta_1^{(0)}(0) & \Delta_1^{(0)}(1) & \ldots & \Delta_1^{(0)}(m-1) \\ \Delta_1^{(1)}(0) & \Delta_1^{(1)}(1) & \ldots & \Delta_1^{(1)}(m-1) \\ \ldots & \ldots & \ldots & \ldots \\ \Delta_1^{(m_1-1)}(0) & \Delta_1^{(m_1-1)}(1) & \ldots & \Delta_1^{(m_1-1)}(m-1) \\ \Delta_{m_1+1}^{(0)}(0) & \Delta_{m_1+1}^{(0)}(1) & \ldots & \Delta_{m_1+1}^{(0)}(m-1) \\ \vdots & \ddots & \ddots & \ldots & \ldots \\ \Delta_{m_1+1}^{(m_2-1)}(0) & \Delta_{m_1+1}^{(m_2-1)}(1) & \ldots & \Delta_{m_1+1}^{(m_2-1)}(m-1) \\ \vdots & \ddots & \ddots & \ddots & \ldots \\ D(0) & D(1) & \ldots & D(m-1) \end{vmatrix},$$

here we use a notation

$$D(j) = \Delta_{m_1 + m_2 + \dots + m_{n-1} + 1}^{(m_n - 1)}(j).$$

By using (2.4), it can be shown that

$$\Phi_{m_1, m_2, \dots, m_n}(\hat{\lambda}_1, \hat{\lambda}_2, \dots, \hat{\lambda}_m) = V_m(\hat{\lambda}_1, \hat{\lambda}_2, \dots, \hat{\lambda}_m) / V_{m_1}(\hat{\lambda}_1, \dots, \hat{\lambda}_{m_1})$$

$$\times V_{m_2}(\hat{\lambda}_{m_1+1}, \dots, \hat{\lambda}_{m_1+m_2}) \cdot \dots \cdot V_{m_n}(\hat{\lambda}_{m_1+\dots+m_{n-1}+1}, \dots, \hat{\lambda}_m).$$

Determinant $\Phi_{m_1,m_2,...,m_n}\left(\hat{\lambda}_1,\hat{\lambda}_2,...,\hat{\lambda}_m\right)$ is a polynomial (not necessarily symmetric) in $\hat{\lambda}_1,\hat{\lambda}_2,...,\hat{\lambda}_m$; besides,

$$\Phi_{m_1,m_2,\ldots,m_n}(\hat{\lambda}_1,\hat{\lambda}_2,\ldots,\hat{\lambda}_m) \neq 0.$$

Now, using the V-set $\{\lambda_1, \lambda_2, \dots, \lambda_n\}$, we can construct the determinant

$$\begin{split} \bar{V}_{m_1,m_2,\dots,m_n} \Big(\lambda_1, \lambda_2, \dots, \lambda_n \Big) &= \\ \Big(\begin{matrix} 0 \\ 0 \end{matrix}) \lambda_1^{0-0} & \begin{pmatrix} 1 \\ 0 \end{matrix}) \lambda_1^{1-0} & \dots & \begin{pmatrix} m-1 \\ 0 \end{matrix}) \lambda_1^{m-1-0} \\ \begin{pmatrix} 1 \\ 1 \end{matrix}) \lambda_1^{0-1} & \begin{pmatrix} 1 \\ 1 \end{matrix}) \lambda_1^{1-1} & \dots & \begin{pmatrix} m-1 \\ 1 \end{matrix}) \lambda_1^{m-1-1} \\ \dots & \dots & \dots & \dots \\ \begin{pmatrix} 0 \\ m_1-1 \end{pmatrix} \lambda_1^{0-m_1+1} & \begin{pmatrix} 1 \\ m_1-1 \end{pmatrix} \lambda_1^{1-m_1+1} & \dots & \begin{pmatrix} m-1 \\ m_1-1 \end{pmatrix} \lambda_1^{m-1-m_1+1} \\ \begin{pmatrix} 0 \\ 0 \end{matrix}) \lambda_2^{0-0} & \begin{pmatrix} 1 \\ 0 \end{matrix}) \lambda_2^{1-0} & \dots & \begin{pmatrix} m-1 \\ 0 \end{matrix}) \lambda_2^{m-1-0} \\ \dots & \dots & \dots & \dots \\ \begin{pmatrix} 0 \\ m_2-1 \end{pmatrix} \lambda_2^{0-m_2+1} & \begin{pmatrix} 1 \\ m_2-1 \end{pmatrix} \lambda_2^{1-m_2+1} & \dots & \begin{pmatrix} m-1 \\ m_2-1 \end{pmatrix} \lambda_2^{m-1-m_2+1} \\ \dots & \dots & \dots & \dots \\ \begin{pmatrix} 0 \\ m_n-1 \end{pmatrix} \lambda_n^{0-m_n+1} & \begin{pmatrix} 1 \\ m_n-1 \end{pmatrix} \lambda_n^{1-m_n+1} & \dots & \begin{pmatrix} m-1 \\ m_n-1 \end{pmatrix} \lambda_n^{m-1-m_n+1} \\ \end{pmatrix} \end{split}$$

Definition 2. $\bar{V}_{m_1,m_2,...,m_n}(\lambda_1,\lambda_2,...,\lambda_n)$ is called the *generalized Van-der-Mond determinant*.

Equality (2.7) implies that

$$\bar{V}_{m_1,m_2,\dots,m_n}(\lambda_1,\lambda_2,\dots,\lambda_n) = \lim_{\substack{\hat{\lambda}_1,\hat{\lambda}_2,\dots,\hat{\lambda}_{m_1} \to \lambda_1 \\ \hat{\lambda}_{m_1+1},\dots,\hat{\lambda}_{m_1+m_2} \to \lambda_2 \\ \hat{\lambda}_{m_1+\dots+m_{n-1}+1},\dots,\hat{\lambda}_m \to \lambda_n}} \varPhi_{m_1,m_2,\dots,m_n}(\hat{\lambda}_1,\hat{\lambda}_2,\dots,\hat{\lambda}_m).$$

Consequently, the generalized Van-der-Mond determinant is a polynomial in $\lambda_1, \lambda_2, \ldots, \lambda_n$, besides, $\bar{V}_{m_1, m_2, \ldots, m_n}(\lambda_1, \lambda_2, \ldots, \lambda_n) \neq 0$.

We notice here that

$$\bar{V}_{1,1,\ldots,1}(\lambda_1,\lambda_2,\ldots,\lambda_n) = V_n(\lambda_1,\lambda_2,\ldots,\lambda_n), \quad \bar{V}_n(\lambda_k) = 1,$$

and so on.

Example 1. Given two V-sets $\{\hat{\lambda}_1, \hat{\lambda}_2, \hat{\lambda}_3\}, \{\lambda_1, \lambda_2\}$, with $m_1 = 2, m_2 = 1$, then we easily derive:

$$\Phi_{2,1}(\hat{\lambda}_1, \hat{\lambda}_2, \hat{\lambda}_3) = \begin{vmatrix} \Delta_1^{(0)}(0) \ \Delta_1^{(0)}(1) \ \Delta_1^{(0)}(2) \\ \Delta_1^{(1)}(0) \ \Delta_1^{(1)}(1) \ \Delta_1^{(1)}(2) \\ \Delta_3^{(0)}(0) \ \Delta_3^{(0)}(1) \ \Delta_3^{(0)}(2) \end{vmatrix} = (\hat{\lambda}_3 - \hat{\lambda}_1)(\hat{\lambda}_3 - \hat{\lambda}_2) \neq 0.$$

Then we get:

$$\bar{V}_{2,1}(\lambda_1, \lambda_2) = \begin{vmatrix} 1 & \lambda_1 & \lambda_1^2 \\ 0 & 1 & 2\lambda_1 \\ 1 & \lambda_2 & \lambda_2^2 \end{vmatrix} = (\lambda_2 - \lambda_1)^2 \neq 0.$$

2.2. The algebraic progressions

In this section, the concept of an algebraic progression – generalization of an arithmetic/geometric progression – is presented. Some properties of the algebraic progressions are disclosed. Let a sequence of complex numbers $(p_j; j \in Z)$ be given. Then, for every $m \in N$ and fixed $j_0 \in Z_0$, it is possible to construct the Hankel matrix $H_{j_0}^{(m)}$ and the extended matrix $\bar{H}_{j_0}^{(m)}(\rho)$ (see [4]):

$$H_{j_0}^{(m)} := \left\| \begin{array}{c} p_{j_0} & p_{j_0+1} & \dots & p_{j_0+m-1} \\ p_{j_0+1} & p_{j_0+2} & \dots & p_{j_0+m} \\ \dots & \dots & \dots & \dots \\ p_{j_0+m-1} & p_{j_0+m} & \dots & p_{j_0+2m-2} \end{array} \right\|,$$

$$\bar{H}_{j_0}^{(m)}(\rho) := \left\| \begin{array}{c} p_{j_0} & p_{j_0+1} & \dots & p_{j_0+2m-2} \\ p_{j_0+1} & p_{j_0+2} & \dots & p_{j_0+m+1} \\ \dots & \dots & \dots & \dots \\ p_{j_0+m-1} & p_{j_0+m} & \dots & p_{j_0+2m-1} \\ 1 & \rho & \dots & \rho^m \end{array} \right\|.$$

DEFINITION 3. If for a sequence of complex numbers $(p_j; j \in Z)$, r_0 satisfies the condition $r_0 = \max_{\substack{m \in N \\ j_0 \in Z_0}} \operatorname{rank} H_{j_0}^{(m)}$, then the rank of the sequence of complex

numbers $(p_i; j \in Z)$ is equal to r_0 .

Let us denote $H_r(p_j; j \in Z) = r_0$.

Example 2. $H_r(a_0 + jd; j \in Z_0) = 2$, provided $d \neq 0$. $H_r(j^2; j \in Z_0) = 3$. It can be proved that $H_r(a_lj^l + a_{l-1}j^{l-1} + \ldots + a_0; j \in Z_0) = l+1$, for $a_l \neq 0, l \in N$. Also, $H_r(a_0, a_1, \ldots a_n, 0, 0, \ldots) = n+1$, for $a_n \neq 0$. Here we assume that $H_r(0, 0, \ldots) = 0$. The sequence $(j!; j \in Z_0)$ doesn't have H_r , because $\det H_m^{(j)} \neq 0$, for all $m \in N$ and $j \in Z_0$.

Some corollaries follow from the definition of H_r .

Corollary 1. Let $q_j = p_{j+n}$, where $n \in N$ is fixed and $m_1 < m_2$. Then

$$H_r(p_j; j \in Z_0) \ge H_r(q_j; j \in Z_0), \quad rank H_{j_0}^{(m_1)} \le rank H_{j_0}^{(m_2)}.$$

Corollary 2. If $H_r(p_j; j \in Z_0) = r_0$, then $\det H_0^{(r_0)} \neq 0$ and $\det H_j^{(r_0+1+n)} \equiv 0$, $j, n \in Z_0$. So, $H_r(p_j; j \in Z_0) = \max_{m \in N} rank H_0^{(m)}$.

Corollary 3. The given sequence $(p_j; j \in Z_0)$ has H_r , satisfying equality

$$H_r(p_i; j \in Z_0) = m, m \in Z_0,$$

if and only if constants $A_0, A_1, \ldots, A_{m-1} \in C$ are independent of j and satisfy the condition

$$A_0 p_j + A_1 p_{j+1} + \ldots + A_{m-1} p_{j+m-1} = p_{j+m}, \quad \forall j \in \mathbb{Z}_0.$$
 (2.8)

Equality (2.8) makes no sense for m' < m.

By taking $j=0,1,\ldots,m-1$ in (2.8) we get a system of linear equations, for finding all coefficients A_0,A_1,\ldots,A_{m-1} . The matrix of this system is equal to $H_0^{(m)}$ and $\det H_0^{(m)} \neq 0$. As example it is possible to prove that for sequence

$$(a_l j^l + a_{l-1} j^{l-1} + \ldots + a_0; j \in Z_0)$$

the coefficients are defined as

$$A_r = (-1)^{l-r} {l+1 \choose r}, \quad r = 0, 1, \dots, l.$$

The correctness of this relationship follows directly from the combinatorial equality, [3]

$$\sum_{l=0}^{l} (-1)^{l-r} {l+1 \choose r} (j+r)^n = (j+l)^n, \quad n = 0, 1, \dots, l; \ l \in \mathbb{N}.$$

Corollary 4. Two sequences of complex numbers, $(p_j; j \in Z_0)$ and $(q_j; j \in Z_0)$ are equal if and only if $H_r(p_j; j \in Z_0) = H_r(q_j; j \in Z_0) = m$ and $p_j = q_j$, for $j = 0, 1, \ldots, 2m - 1$.

Lemma 1. Let $(p_i; j \in Z_0)$ be a sequence and

$$p_j := \sum_{r=1}^m \mu_r \lambda_r^j. \tag{2.9}$$

Let $\{\lambda_1, \ldots, \lambda_m\}$ be a V-set. Then we get the following equalities:

$$\det H_i^{(m)} = (\mu_1 \mu_2 \cdots \mu_m)(\lambda_1 \lambda_2 \cdots \lambda_m)^j V_m^2(\lambda_1, \lambda_2, \cdots, \lambda_m), \qquad (2.10)$$

$$\det \bar{H}_j^{(m)}(\rho) = \det H_j^{(m)}(\rho - \lambda_1)(\rho - \lambda_2) \cdots (\rho - \lambda_m). \tag{2.11}$$

Proof. Really.

$$\det H_j^{(m)} = (\mu_1 \mu_2 \cdots \mu_m) (\lambda_1 \lambda_2 \cdots \lambda_m)^j \sum_{(r_1, r_2, \dots, r_m)} \det \|\lambda_{r_k}^{k+l-2}\|_{k, l=1}^m, \quad (2.12)$$

where summation is performed over all possible permutations (r_1, r_2, \ldots, r_m) of integer numbers $1, 2, \ldots, m$. Since

$$\sum_{(r_1, r_2, \dots, r_m)} \det \|\lambda_{r_k}^{k+l-2}\|_{k, l=1}^m = (\det \|\lambda_k^{l-1}\|)^2, \quad k, l = 1, \dots, m,$$

the proof of identity (2.10) is obtained. The proof of identity (2.11) is carried out in a similar way.

Remark 1. For all V-sets $\{\lambda_1, \lambda_2, \dots, \lambda_n\}$, the relationship $(\lambda_1 \lambda_2 \cdots \lambda_m)^0 = 1$ is valid.

Corollary 5. If p_j is specified by (2.9), then $\det H_j^{(m)} \equiv 0$ for all $j \in Z_0$ and $n \geq m+1$. Therefore, $H_r(p_j; j \in Z) = m$, provided $\mu_1, \mu_2, \ldots, \mu_m \neq 0$.

Now, using V-set $\{\lambda_1, \lambda_2, \dots, \lambda_n\}$, it is possible to form a sequence of numbers $(p_j; j \in Z_0)$, which is given by

$$p_{j} := \sum_{r=1}^{n} \sum_{k=0}^{m_{r}-1} \mu_{rk_{r}} {j \choose k_{r}} \lambda_{r}^{j-k_{r}}, \quad m_{1}, m_{2}, \dots, m_{n} \in N, \ \mu_{rk_{r}} \in C.$$
 (2.13)

DEFINITION 4. The sequence of numbers, specified by (2.13), is called the algebraic progression, the coefficients $\lambda_1, \lambda_2, \ldots, \lambda_n$ are said to be denominators of multiplicity m_1, m_2, \ldots, m_n , respectively, and μ_{rk_r} are called coefficients of the algebraic progression.

Remark 2. The sequences of numbers, proposed in the above examples and specified by (2.9), are algebraic progressions. Respective denominators can be found immediately. For instance, denominators of the sequence $(p_j; j \in Z_0)$,

$$p_j = a_0 + jd$$
, are given by $\lambda_{1,2} = 1$, i.e., $p_j = a_0 1^j + d(\frac{j}{1})1^{j-1}$.

Thus, arithmetic and geometric progressions are algebraic progressions. Notice that the sequence

$$(\Delta_k^{(r)}(j), j \in Z_0), r = 1, 2, \dots, m - k$$

is an algebraic progression, besides,

$$H_r(\Delta_k^{(r)}(j), j \in Z_0) = r + 1.$$

For instance, by using identity (2.10), the limit calculus and relationships (2.1) we observe that H_r of the sequence of numbers $\binom{j}{l} \lambda_k^{j-l}$, $j \in Z_0$ satisfies the relationship:

$$H_r(\binom{j}{l}\lambda_k^{j-l}, j \in Z_0) = l+1,$$

besides,

$$\det H_j^{(r+1)} = \begin{cases} \binom{l+1}{2} \\ (-1) & \lambda_k^{(l+1)\cdot j}, \ r = l, \\ 0, \ r \ge l+1. \end{cases}$$

Really, lemma 1 and relationships (2.5) and (2.6) imply that the determinant $\det H_j^{(l+1)}$ of the Hankel matrix $H_j^{(l+1)}$ for the algebraic sequence $(\Delta_k^{(r)}(j), j \in Z_0)$ can be expressed as follows:

$$\det H_j^{(l+1)} = (-1)^{\binom{l+1}{2}} \frac{V_l(\hat{\lambda}_k, \dots, \hat{\lambda}_{k+l-1}) \cdot \dots \cdot V_l(\hat{\lambda}_{k+1}, \dots, \hat{\lambda}_{k+l})}{V_{l+1}^{l+1}(\hat{\lambda}_k, \dots, \hat{\lambda}_{k+l})}$$

$$\times (\hat{\lambda}_k, \dots, \hat{\lambda}_{k+l})^j \cdot V_{l+1}^2(\hat{\lambda}_k, \dots, \hat{\lambda}_{k+l}) = (-1)^{\binom{l+1}{2}} (\hat{\lambda}_k, \dots, \hat{\lambda}_{k+l})^j.$$

Then,

$$\lim_{\lambda_k,\dots,\hat{\lambda}_{k+l}\to\lambda_k} \det H_j^{(l+1)} = (-1)^{\binom{l+1}{2}} \lambda_k^{(l+1)j}.$$

By taking into account properties of $\Delta_k^{(r)}(j)$ we state that expression (2.13) can be derived from (2.9) by passing to the limit:

$$\lim_{\substack{\hat{\lambda}_1, \hat{\lambda}_2, \dots, \hat{\lambda}_{m_1} \to \lambda_1, \\ \hat{\lambda}_{m_{1+1}}, \dots, \hat{\lambda}_{m_1+m_2} \to \lambda_2, \\ \dots \\ \hat{\lambda}_{m_1+1}, \dots, \hat{\lambda}_{m_1+1}, \dots, \hat{\lambda}_m \to \lambda_n}} \sum_{k_1=0}^{m_1-1} \mu_{1k_1} \Delta_1^{(k_1)}(j) + \sum_{k_2=0}^{m_2-1} \mu_{2k_2} \Delta_{m_1+1}^{(k_2)}(j) + \dots$$

$$+\sum_{k_n=0}^{m_n-1} \mu_{nk_n} \Delta_{m_1+\ldots+m_{n-1}+1}^{(k_n)}(j) = \sum_{r=1}^n \sum_{k_r=0}^{m_r-1} \mu_{rk_r} (\frac{j}{k_r}) \lambda_r^{j-k_r} = p_j,$$

where $m_1 + m_2 + \ldots + m_n = m$; besides, $\{\lambda_1, \lambda_2, \ldots, \lambda_n\} \in C$ is a V-set. Then, $H_r(p_j; j \in Z_0) = m$.

Corollary 6. If the j-th term p_j of the algebraic progression $(p_j; j \in Z_0)$ is described by (2.13), then Hankel matrices $H_j^{(m)}$ and $\bar{H}_j^{(m)}$ satisfy relationships:

$$\det H_j^{(m)} = \sigma_m (\lambda_1^{m_1} \lambda_2^{m_2} \dots \lambda_n^{m_n})^j,$$

$$\det \bar{H}_j^{(m)} = \det H_j^{(m)} (\rho - \lambda_1)^{m_1} (\rho - \lambda_2)^{m_2} \dots (\rho - \lambda_n)^{m_n},$$

provided $\sigma_m = \det H_0^{(m)} \neq 0$ and $\det H_j^{(m)}$ is independent of j, i.e.

$$\sigma_{m} = (-1)^{\binom{m_{1}}{2} + \binom{m_{2}}{2} + \ldots + \binom{m_{n}}{2}} \mu_{1m_{1}-1}^{m_{1}} \mu_{2m_{2}-1}^{m_{2}} \ldots \mu_{nm_{n}-1}^{m_{n}} \times \bar{V}_{m_{1},m_{2},\ldots,m_{n}}^{2} \left(\lambda_{1},\lambda_{2},\ldots,\lambda_{n}\right).$$

Theorem 1. H_r of the algebraic progression $(p_j; j \in Z_0)$, specified by (2.13), satisfies the relationship:

$$H_r(p_j; j \in Z_0) = m_1 + m_2 + \ldots + m_n$$
, where $\mu_{rm_{r-1}} \neq 0$.

The following two conclusions can be made.

Corollary 7. Let $(p_j; j \in Z_0)$ and $(q_j; j \in Z_0)$ be two algebraic progressions and $a, b \in C$ are fixed numbers. Then

$$(ap_j + bq_j; j \in Z_0), (p_jq_j; j \in Z_0), (ap_j^2 + bq_j; j \in Z_0), \dots$$

are algebraic progressions and

$$H_r(ap_j + bq_j; j \in Z_0) \le H_r(p_j; j \in Z_0) + H_r(q_j; j \in Z_0);$$

$$H_r(p_jq_j; j \in Z_0) \le H_r(p_j; j \in Z_0) H_r(q_j; j \in Z_0).$$

Corollary 8. Let $H_j^{(m)}$ be Hankel matrices of algebraic progression $(p_j; j \in Z_0)$. Then, $(\det H_j^{(m)}; j \in Z_0)$ are algebraic progressions, for all $m \ge 1$.

Theorem 2. If a sequence of complex numbers $(p_j; j \in Z_0)$ has

$$H_r(p_j; j \in Z_0) = m < +\infty,$$

then this sequence is an algebraic progression.

Proof. First, using (2.8), a system of linear equations is formed. The matrix of this system is given by $H_0^{(m)}$, and $\det H_0^{(m)} \neq 0$. Then coefficients $A_0, A_1, \ldots, A_{m-1}$ are found. Expending the determinant $\det \bar{H}_0^{(m)}(\rho)$ with respect to the last row, we get

$$\det \bar{H}_0^{(m)}(\rho) = \det H_0^{(m)}(A_0 + A_1\rho + \ldots + A_{m-1}\rho^{m-1} - \rho^m).$$

Let roots $\lambda_1, \lambda_2, \ldots, \lambda_n$ of the algebraic equation $\bar{H}_0^{(m)}(\rho) = 0$ be of multiplicity m_1, m_2, \ldots, m_n respectively (here, $m_1 + m_2 + \ldots + m_n = m$). Then, from (2.13) we obtain

$$\rho^{m+j} - A_{m-1}\rho^{m-1+j} - \ldots - A_0\rho^j = \rho^j(\rho - \lambda_1)^{m_1} \cdot \ldots \cdot (\rho - \lambda_n)^{m_n}, j \in \mathbb{Z}_0,$$

and

$$\binom{j+m}{k}\lambda_r^{m+j-k} = A_{m-1}\binom{j+m-1}{k}\lambda_r^{m+j-1} + \ldots + A_0\binom{j}{k}\lambda_r^{m-k},$$

for r = 1, 2, ..., n, $k = 0, 1, ..., m_r - 1, j \in \mathbb{Z}_0$. Since the determinant of the coefficient matrix of the constructed linear system

$$\sum_{r=1}^{n} \sum_{k_{r}=0}^{m_{r}-1} {j \choose k_{r}} \lambda_{r}^{j-k_{r}} \mu_{rk_{r}} = p_{j}, \quad j = 0, 1, \dots, m-1,$$

represents a non-zero generalized Van-der-Mond determinant, there are no problems to find the coefficients μ_{rk_r} and to form the algebraic progression $(q_j; j \in Z_0)$ described by the relationship

$$q_j := \sum_{r=1}^{n} \sum_{k_r=0}^{m_r-1} \mu_{rk_r} {j \choose k_r} \lambda_r^{j-k_r}, \ j \in N.$$

The equality $q_j = p_j$ holds true for j = 0, 1, ..., m - 1. Besides, taking successively j = 0, 1, ..., m - 1, we find out

$$q_{j+m} = \sum_{r=1}^{n} \sum_{k_r=0}^{m_r-1} \mu_{rk_r} {j+m \choose k_r} \lambda_r^{j+m-k_r}$$

$$= A_{m-1} \left(\sum_{r=1}^{m} \sum_{k_r=0}^{m_r-1} \mu_{rk_r} {j+m-1 \choose k_r} \lambda_r^{j-k_r} \right) + \dots$$

$$+ A_0 \left(\sum_{r=1}^{m} \sum_{k_r=0}^{m_r-1} \mu_{rk_r} {j \choose k_r} \lambda_r^{j-k_r} \right) = A_{m-1} p_{j+m-1} + A_0 p_j = p_{j+m}.$$

Thus, $q_j = p_j$, for $j = m, \ldots, 2m - 1$. Now, the above corollaries imply that $p_j = q_j$, for $j \in \mathbb{Z}_0$.

Remark 3. The proof of Theorem 2 gives us a computational algorithm for finding all denominators of the algebraic progression and coefficients of the progression.

2.3. The algebraic functions

In this section a special type of analytical functions (algebraic functions with finite rank) is described. The relationships between these functions and algebraic progressions is established.

Let a power series of a real variable x be given

$$y(x) = \sum_{j=0}^{+\infty} p_j \frac{(x - x_0)^j}{j!}, \quad |p_j| \le M^j, \quad 0 \le M < \infty.$$
 (2.14)

This series is convergent for all values of $x, x_0 \in R$ (x_0 being fixed).

DEFINITION 5. A function, specified by (2.14), is called an *algebraic function* with finite rank, if it can be represented as a finite sum:

$$y(x) = \sum_{r=1}^{n} Q_r(x)e^{\lambda_r x},$$
(2.15)

where

$$Q_r(x) = \sum_{k_r=0}^{m_r-1} a_{rk_r} x^{k_r}, \quad m_r \ge 1, \quad a_{rk_r} \in C,$$

besides, $a_{rm_r-1} \neq 0$.

Theorem 3. Power series (2.14) can be reduced to the form (2.15) if and only if coefficients p_j in (2.14) represent an algebraic progression $(p_j; j \in Z_0)$; besides, $H_r(p_j; j \in Z_0) = m_1 + m_2 + \ldots + m_n$.

Proof. The proof is based on the following transformations:

$$x^l e^{\lambda x} = x^l \sum_{j=0}^{+\infty} \frac{(\lambda x)^j}{j!} = (l!) \sum_{j=0}^{+\infty} \binom{j}{l} \lambda^{j-l} \frac{x^j}{j!}.$$

Corollary 9. Algebraic function y(x) (expression (2.15)) can be reduced to the form

$$y(x) = \mu_0 + \sum_{r=1}^{m} (\mu_r \cos(\lambda_r(x - x_0)) + \gamma_r \sin(\nu_r(x - x_0))),$$

if and only if the sequence $(p_j; j \in Z_0)$ is an algebraic progression, satisfying relationships (2.9), besides, the real parts of its denominators are zeros.

Corollary 10. If sequence $(p_j; j \in Z_0)$ is an algebraic sequence, then the series (2.14) is convergent, for all $x \in R$.

Based on the above theorems and corollaries, the following conclusion can be made.

Corollary 11. Let function y(x) be specified by power series (2.14) and it satisfies relationships (2.15). Then sequence

$$(\hat{p}_k; k \in Z_0), \quad \hat{p}_k := y(kh + x_0), \ h, x_0 \in R$$

is an algebraic progression with denominators $\Lambda_r = e^{h\lambda_r}$, $r = 1, \ldots, n$, if λ_r are the denominators of algebraic progression $(p_j; j \in Z_0)$ and they compose a V-set. In general case a set $\{\Lambda_1, \Lambda_2, \ldots, \Lambda_n\}$ is not a V-set, i.e. some Λ_{r_1} , Λ_{r_2} can satisfy the relationship $\Lambda_{r_1} = \Lambda_{r_2}$, when $r_1 \neq r_2$, besides, $\Lambda_r \neq 0$, $r = 1, 2, \ldots, n$. As a result, we get

$$H_r(\hat{p}_k; k \in Z_0) \le H_r(p_j; j \in Z_0).$$

3. Applications

Let a solution of a differential equation is given, i.e.:

$$f(t) = \sum_{k=0}^{+\infty} p_k \frac{t^k}{k!}, \quad k = 0, 1, 2, \dots, t \in R.$$

We are interested in representing this solution as a finite sum of exponential functions, namely:

$$f(t) = \sum_{r=1}^{m} \mu_r e^{\lambda_r t}.$$
 (3.1)

The following fact is taken into consideration

$$\max(l: l \in N, \ det H_0^{(m)} \neq 0) = m.$$
 (3.2)

Next, by using some methods of linear algebra, we find coefficients μ_r and λ_r in expression (3.1) from

$$\det \bar{H}_0^{(m)}(\rho) = 0, \quad p_k = \sum_{r=0}^m \lambda_r^k \mu_r, \quad k = 0, 1, 2, \dots, m - 1.$$

Suppose, $\rho_1, \rho_2, \dots, \rho_m$ is V-set. Then, $\rho_k = \lambda_k, k = 1, 2, \dots, m$.

Example 3. Let

$$y(x) = 2\sum_{k=0}^{+\infty} 3^{k-1} \frac{x^{2k}}{(2k)!} + \sum_{k=0}^{+\infty} 3^k \frac{x^{2k+1}}{(2k+1)!}$$

be a solution of a differential equation. Obviously, the power series coefficients are:

$$p_j = \begin{cases} 2 \cdot 3^{k-1}, & j = 2k, \\ 3^k, & j = 2k+1, \end{cases} \qquad k = 0, 1, 2 \dots$$

and $H_r(p_j; j \in Z_0) = 2$. Condition (3.2) implies

$$\begin{vmatrix} p_0 & p_1 & p_2 \\ p_1 & p_2 & p_3 \\ 1 & \rho & \rho^2 \end{vmatrix} = -(\rho^2 - 3) = 0, \quad \lambda_1 = \sqrt{3}, \quad \lambda_2 = -\sqrt{3},$$

i.e.

$$y(x) = \mu_1 e^{\sqrt{3}x} + \mu_2 e^{-\sqrt{3}x}, \quad \begin{cases} \mu_1 + \mu_2 = 2/3, \\ \mu_1 \sqrt{3} - \mu_2 \sqrt{3} = 1. \end{cases}$$

Thus,

$$\mu_{1,2} = \frac{2 \pm \sqrt{3}}{6}, \quad y(x) = \frac{2 + \sqrt{3}}{6}e^{\sqrt{3}x} + \frac{2 - \sqrt{3}}{6}e^{-\sqrt{3}x}.$$

Example 4. Let a system of ordinary differential equations

$$\begin{cases} l\varphi'' - x'' \sin \varphi + H\varphi' = 0, \\ x'' + p^2 x - q_1 x' + q_3 x'^3 - \mu(\varphi'' \sin \varphi + \varphi'^2 \cos \varphi) = 0 \end{cases}$$
(3.3)

be given. Here H, p, q_1, q_3, μ are parameters, whose numerical values should be chosen to provide autonomous vibration x(t) and to stimulate rotational motion $\varphi = \varphi(t)$. In particular, H is a dissipative coefficient, p stands for the self frequency of the system, q_1 and q_3 are self-vibration parameters, μ express the mass of rotor.

One of the main steady modes of the system is characterized by the uniform rotation of the rotor. For instance, such a mode is ensured if the parameter values are chosen to be

$$H = 0.05, \ \mu = 0.1, \ p = 1, \ q_1 = 0.5, \ q_3 = 1.75$$

and initial conditions

$$x(0) = x'(0) = 0.1, \quad \varphi(0) = 0.1, \quad \varphi'(0) = 1.$$

By applying the operator method we get the following result (see [1])

$$\varphi'(t) = 0.7678 + 0.0531t + 0.2877t^2 - 0.0309t^3 - 0.0839t^4 + 0.0054t^5 + 0.0098t^6 - \dots$$

By using the adapted operator method, we obtained a finite sum of trigonometric functions

$$\tilde{\varphi}'(t) = 0.9324 + 0.1646\cos 1.87t - 0.0283\sin 1.87t. \tag{3.4}$$

The accuracy of the approximation is up to four decimal places.

Since the proposed method discloses influence of higher harmonics to the solutions obtained, it appears to be easier to find out other dynamical characteristics and existence domains for stable modes.

Example 5. Let the function

$$y(x) = \sum_{j=0}^{+\infty} p_j \frac{x^j}{j!} = 0.093e^x - 7^{0.2}e^{-0.2x} - 20.124e^{2.13x} + 5^{\frac{1}{12}}e^{2^{\frac{7}{20}}x}$$
$$-\cos(\sqrt{2})e^{-0.1e^{\sqrt{2}}x} - 0.082e^{0.06x} + \sqrt{7}e^{-0.7x}$$
$$+ 0.175e^{0.801x} + \frac{1}{2}\pi e^{-0.914x} + \sqrt{2}\sqrt{\pi}e^{-2.18\sqrt{5}x}$$

be a solution of a certain differential equation.

In this case $H_r(p_j; j \in Z_0) = 11$. Let us suppose that only the values of this function $y(0.4k) = \hat{p}_k, k \in Z_0$ are known. The determinants $\det H_0^{(k)}$ of matrices $H_0^{(k)}, k = 0, 1, 2, \ldots$ which are composed using sequence $(\hat{p}_k; k \in Z_0)$ vanish monotonically. Then it is estimated that $\det H_0^{(6)} := 0$, as really $\det H_0^{(6)} \approx 10^{-5}$. The estimation $y_0(x)$ of function y(x) is computed:

$$y_0(x) = \sum_{j=0}^{+\infty} q_j \frac{x^j}{j!} = 2.51e^{-4.88x} + 3.67e^{-0.83x} - 20.65e^{0.3x} + 0.55e^{1.19x} + 0.62e^{1.31x}.$$

It is noticed that $H_r(q_j; j \in Z_0) = 5$, besides,

$$|y_0(x) - y(x)| < 10^{-6}, \quad x \in [-1, 1].$$

4. Conclusions

Some new concepts, associated with functions and sequences of series coefficients, are introduced. Conditions for the representation of power series as a finite sum of standard functions are formulated. Usable expressions and computational simplifications for the coefficients of a dynamical system are developed. The method can be applied to both the detection of existence domains for the solutions of stable differential equations and the analysis of the influence of higher harmonics to the type of the solution.

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